



Testing framework for Automated Driving

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Motivation and Introduction

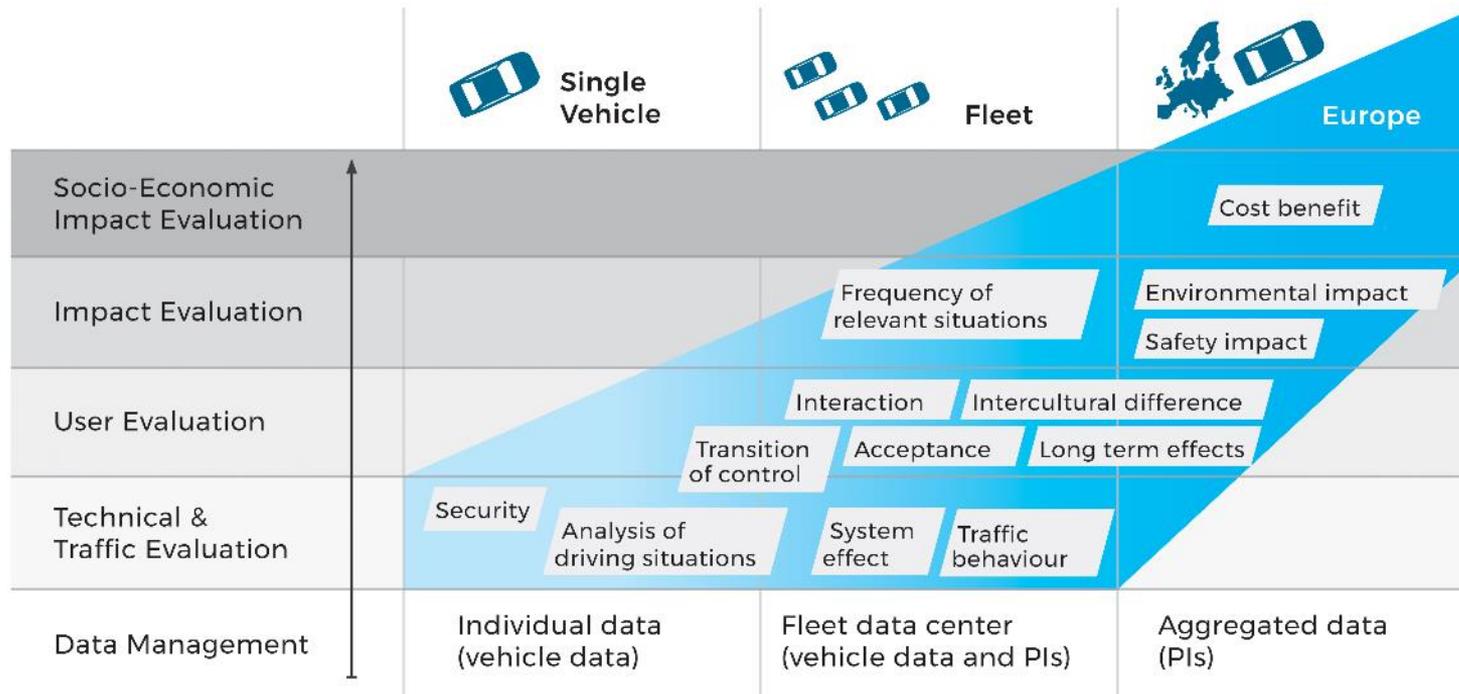
- AD requires new testing framework and new test methodology
- Scenario based testing is key
- Collection of scenarios in database for evaluation
- Focus in L3Pilot
 - Technical & Traffic evaluation
 - User evaluation
 - Impact Assessment and Socio-economic Impact Assessment
- Focus in PEGASUS family
 - Safety assurance

Test Cases

- **Functional based test cases** are derived from functions at the beginning of the development process
 - Strong focus on use cases (Quadrant I)
 - Known safe conditions (Quadrant III) can be analysed
 - Safe unknown conditions are not a big problem (Quadrant IV)
 - Impossible to identify unsafe unknown conditions (Quadrant III)
- Currently **scenario based** approaches are in focus
 - Independent of function
 - Can be defined by third party
- Need of methodology for **unknown unsafe conditions**
 - → **Data based scenarios** → **Database!**

	Condition Present	Condition Absent
Positive Results → safe / passed	I Known safe conditions	II Unknown safe conditions
Negative Results → Unsafe / failed	III Known unsafe conditions	IV Unknown unsafe condition

Evaluation Use Cases in L3Pilot



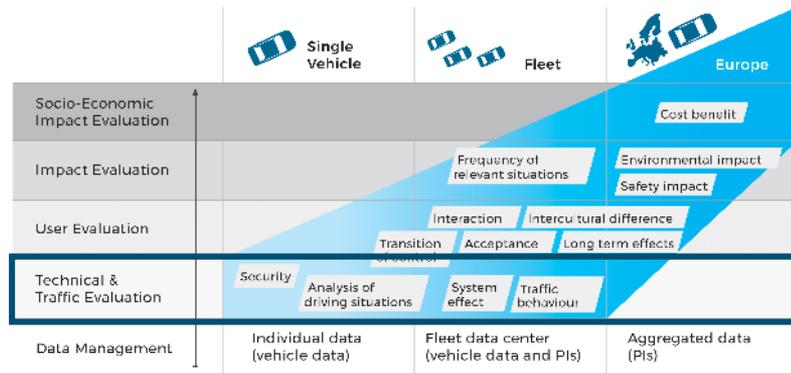
Technical & Traffic Evaluation

Technical:

- How does the AV behave in certain driving situations?
 - How smooth are lane changes?
 - How well does the AV keep a distance?
 - How often do take over requests occur?

Traffic:

- What situations does the AV encounter?
 - How frequent are e.g. *Cut-In* situations?



Key to success:

The right level of aggregation

- Do not look the entire trip in detail
- Define *Performance Indicators for Driving Scenarios*

Technical and Traffic Evaluation Workflow Analysis

- Automated toolchain for data evaluation
- Developed collaboratively by all analysis partners using a shared code repository



From **signals**

- As defined in L3Pilot Common data Format

To **derived measures** (DMs)

- Used for in depth evaluation of data

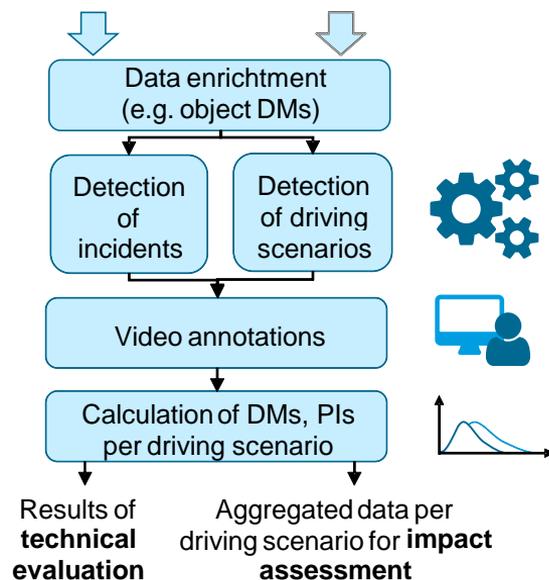
To **performance indicators** (PIs)

- Answering research questions

Driver
(*Baseline*)

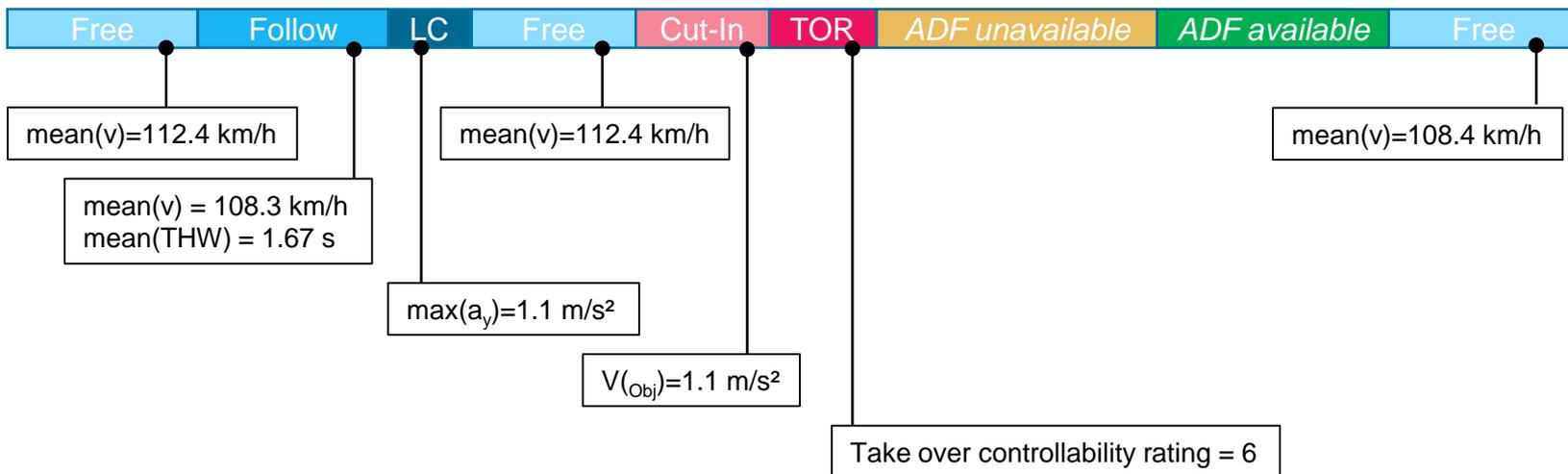


ADF
(*Treatment*)



Technical and Traffic Evaluation Scenario-based Assessment

- Automated scenario detection deriving performance indicator per encountered scenario



Technical and Traffic Evaluation Scenario-based Assessment

- Automated scenario detection deriving performance indicator per encountered scenario
- Further performance indicators are evaluated on trip level



% ADF available	78 %
% ADF active	72 %
Frequency of take over requests	23 / 1000 h

Technical and Traffic Evaluation Scenario-based Assessment

- Automated scenario detection deriving performance indicator per encountered scenario
- Further performance indicators are evaluated on trip level
- Analysis and re-simulation of relevant situation for safety impact assessment



vego, init	78 %
vobj, init	72 %
Dobj, init	23 / 1000 h

Technical and Traffic Evaluation Scenario-based Assessment

- Automated scenario detection deriving performance indicator per encountered scenario
- Further performance indicators are evaluated on trip level
- Analysis and re-simulation of relevant situation for safety impact assessment
- Evaluation of all performance indicators using consolidated database
 - Answering research question on EU-level using data from all pilot sites
 - Entries are pseudoneumized
 - No vehicle owner can be identified

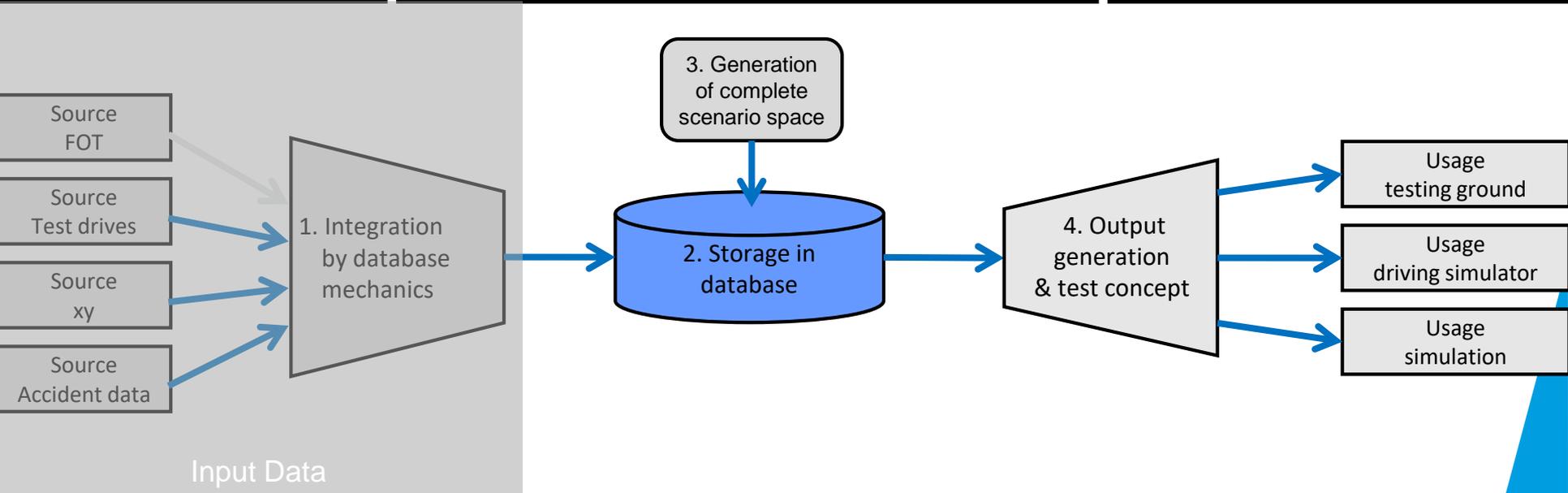
Database for Scenario based Testing

Data with
traffic events

(Logical) scenario

(Logical) scenario with parameter distributions

Concrete scenario



Upload Process for Data into the Database



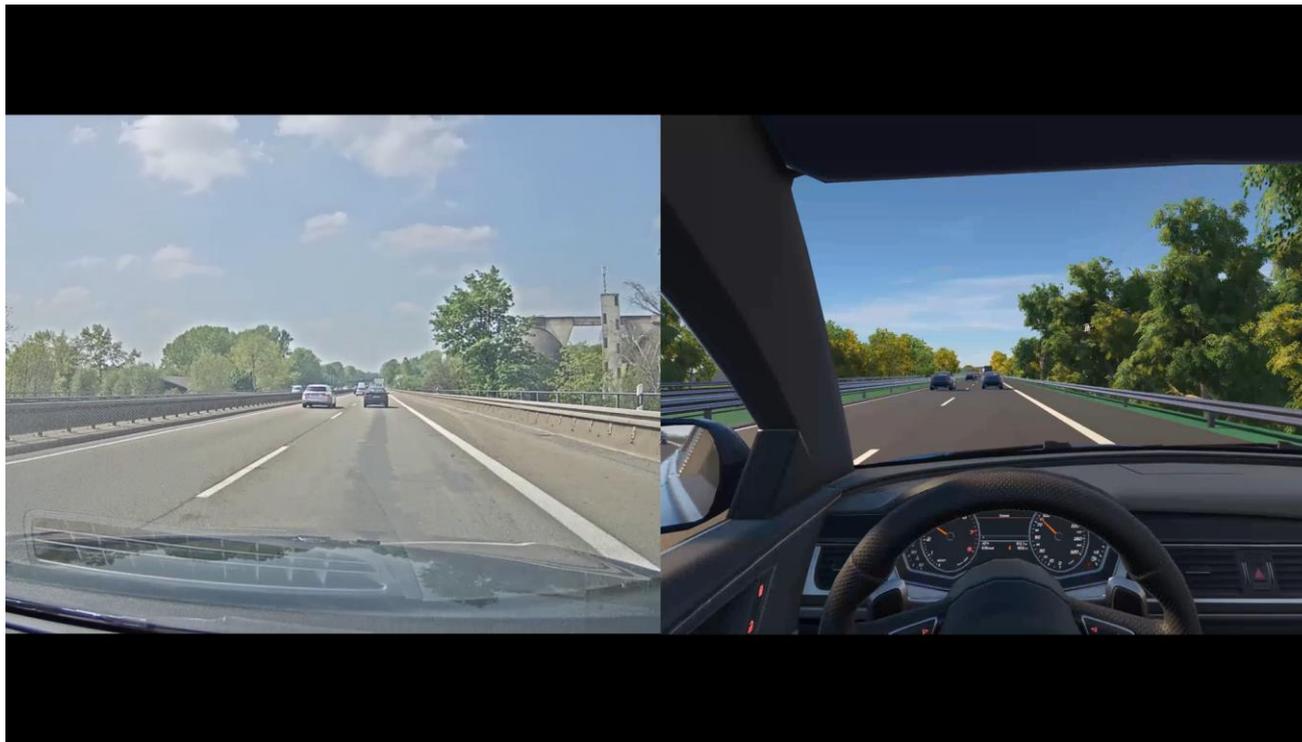
- ✓ Signals according to JSON definitions
- ✓ Minimum requirements on dataset
- ✓ Format: 🇩🇪 Mat or HDF5



Converting to JSON signal definition

Database Upload

Testing of a Concrete Scenario in Simulation



- The selected concrete scenario can be reproduced in the simulation. A HAD-function integrated in the simulation can be tested.
- Here: “Slower turn into path challenger” (see screen 1)

Testing of a Concrete Scenario on the Test Track



- The selected concrete scenario can be reproduced on the test track. A HAD-function integrated in VUT can be tested.
- Here: “Slower turn into path challenger” (see screen 1)

User Evaluation

Data evaluation – Use Cases

User Acceptance:

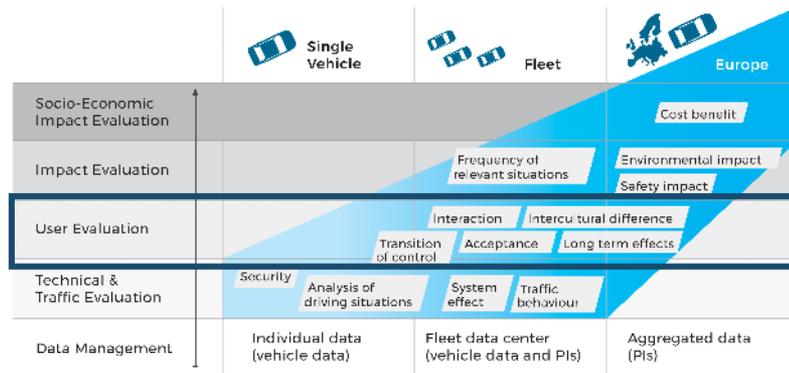
- What is the user's experience with the system?
- What is the user's attitude towards AD?

→ *Questionnaires*

Interaction and transition of control:

- How fast does the driver retake control?
- How attentive is the driver in AD mode?

→ *Coded videos*



Anonymous data required:

- Handling must comply with GDPR!
- Regional differences need to be eliminated

Impact Evaluation

Data evaluation – Use Cases

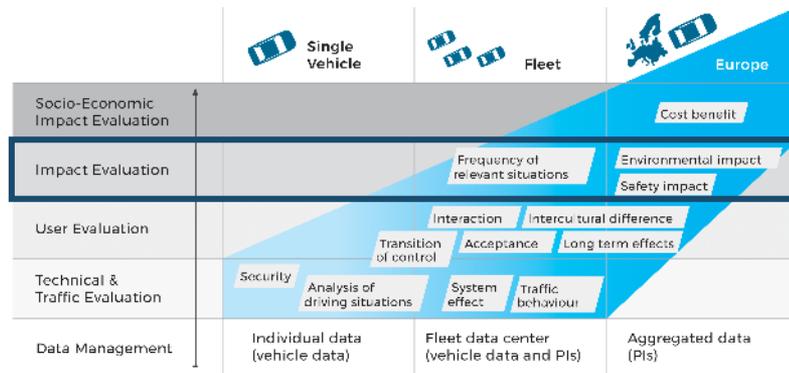
What is the impact of AD on ...

Safety?

- Resimulate situations encountered during piloting
- Vary parameters to increase the amount of available data

Efficiency?

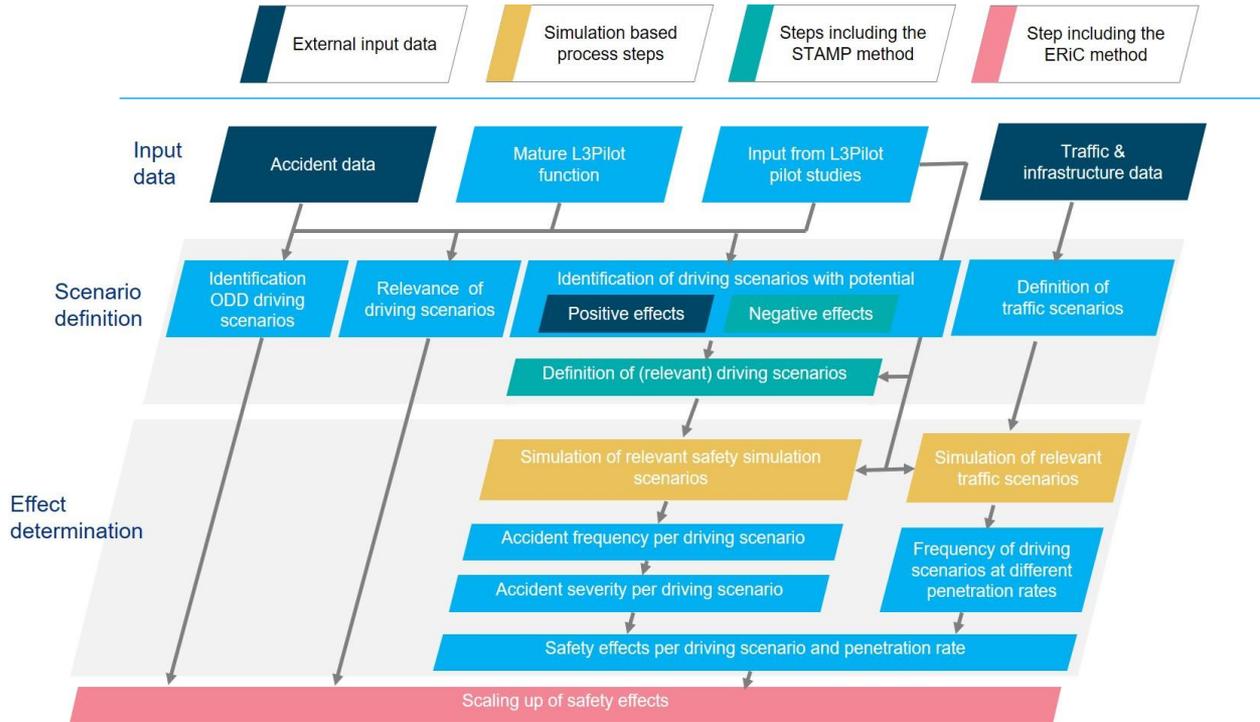
- Simulate traffic with the AV behaviour you observed in traffic
- Consider different penetration rates of AVs



Using piloting data for simulations:

- Simulations need to be in line with pilot results
- But consider that functions are not series-ready yet
- Form requirements together with simulation experts.

Impact Evaluation Methodology for Safety Impact Assessment





Thank you for your kind attention.

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